

**MAGNETIC RECORDING GMR READ BACK SENSOR  
AND METHOD OF MANUFACTURING**

RELATED APPLICATIONS

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FIELD OF THE INVENTION

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The present invention relates to a sensor used in a  
disk drive as a magnetic read back sensor and a  
manufacturing method thereof.

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DESCRIPTION OF THE BACKGROUND ART

Magnetic sensors used in disk drives or tape drives  
for reading back magnetically recorded information are  
usually based on thin film structures utilizing a  
20 magnetoresistive effect. In particular, recent sensors are  
based on a spin dependent scattering phenomenon and are  
generally called giant magnetoresistive (GMR) sensors or  
spin valve sensors. These sensors depend on having one

magnetic layer, called the free layer, in which the direction of magnetization is free to move in response to the magnetic field applied to the sensor. Another layer is called the pinned layer, in which the direction of magnetization is not free to move and is perpendicular to the direction of the magnetization of the free layer when there is no applied external field. In order to achieve maximum sensitivity and linearity, it is required that the magnetization of the free layer in the absence of an applied field to be substantially parallel with the direction of the recorded track. Accordingly it is required that the magnetization in the pinned layer be substantially perpendicular to the recorded track.

Another requirement for the free layer is that there be longitudinal magnetic bias stabilization. Imposing a preferred magnetization direction in the free layer along the axis of the free layer parallel to the medium and perpendicular to the direction of the track insures good linearity and provides robustness to deleterious effects such as Barkhausen noise.

A common method of providing for pinning the pinned layer is to place a layer of antiferromagnetic material, AFM, adjacent to the pinned layer. Then, at some point in

the manufacture of the head, the structure is heated above the blocking temperature of the AFM, and an external field is placed on the device which is perpendicular to the recorded track direction. The blocking temperature of an  
5 AFM material is the temperature above which the material no longer has any exchange coupling strength. The structure is then cooled in the presence of the field. The applied field will orient the pinned layer in the proper direction and as the AFM cools below the blocking temperature exchange  
10 coupling will maintain the orientation of the magnetization in the pinned layer. This is the pinning process.

There are at least two possible techniques to provide for longitudinal biasing of the free layer. A common method is to provide two hard magnets, one on each side of the  
15 portion of the free layer which defines the track width. This is referred to as hard biasing. During the manufacture of the sensor, the direction of the magnetization in the hard magnet must be set by placing the sensors in a large magnetic field. The hard bias method has some undesirable  
20 attributes such as gradual reduction of sensitivity at track edges and is somewhat difficult to control in manufacturing.

Another method of providing for longitudinal biasing

of the free layer is to use an AFM layer to deliver exchange coupling similar to that for the pinned layer. The principle difficulty with this approach is that the direction of magnetization in the free layer must be

5 substantially perpendicular to the direction of magnetization in the pinned layer. Thus the steps of heating and subsequent cooling in a field would be appropriate for one of the AFM layers, but not the other. To solve this problem in the past, two different AFM

10 materials have been used which had distinctly different blocking temperatures. The AFM layer with the highest blocking temperature was set first. Then the field angle was rotated 90° and the second AFM layer was set at a lower temperature. For reasons of magnetic performance and

15 manufacturability there is generally one optimum AFM material which would serve for both pinned and longitudinal stabilization. However because of the requirement to have AFM materials with different blocking temperatures, the optimum choice of AFM materials was compromised.

SUMMARY OF THE INVENTION

One object of the present invention is to provide a  
5 GMR sensor which has an AFM layer for pinning the pinned  
layer and another AFM layer for longitudinal stabilization  
of the free layer. Another object is to provide a sensor  
which can be constructed such that the two AFM layers can  
have substantially the same blocking temperature. Thus, the  
10 sensor can have the two AFM layers made of the same  
material. Typically there is a limited number of AFM  
materials which would be optimum choices for both layers  
based on other considerations such as ease of  
manufacturing, sensor sensitivity, thermal stability, etc.  
15 Another object is to provide a greatly simplified  
manufacturing process in which the two AFM layers can be  
set simultaneously during a single sequence of heating and  
subsequent cooling in a magnetic field. Another object is  
to provide a disk drive having a GMR sensor using two AFM  
20 layers.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 shows a perspective view of a slider head  
5 assembly used in magnetic recording in a disk drive.

Fig. 2a shows a cross sectional view of the layers in  
a sensor which has a single pinned layer.

Fig. 2b shows a cross sectional view of the layers in  
a sensor which has a single pinned layer including views of  
10 the bias current direction and the shields.

Fig. 3 shows a cross sectional view of the layers in a  
sensor which has a set of antiparallel layers for the  
composite pinned layer.

Fig. 4a shows an exploded view of the magnetization  
15 directions in the free layer and the two magnetic layers  
comprising the pinned layer of a sensor while in the  
presence of a high external magnetic field according to an  
embodiment of the present invention.

Fig. 4b shows an exploded view, similar to Fig. 4a, of  
20 the directions of magnetization in the layers while in the  
presence of a medium external magnetic field.

Fig. 4c shows an exploded view, similar to Fig. 4a and  
4b, of the directions of magnetization in the layers while

in the optimum field.

Fig. 4d shows a plot of the angle as a function of external field magnitude for one particular head design.

Fig. 5 shows a view of the layers in a sensor which  
5 has a set of antiparallel layers for the bias tabs and a simple pinned layer.

Fig. 6 shows a view of the layers in a sensor which has exchange biased antiparallel coupled layers for both the pinned layer and the bias tabs.

10 Fig. 7 shows a GMR sensor wherein the width of the layers in the sensor approximately defines the magnetic trackwidth.

Fig. 8a shows a cross section view of a recording device using the invented sensor.

15 Fig. 8b shows a top view of a recording device using the invented sensor.

DETAILED DESCRIPTION OF THE INVENTION

In Fig. 1 a diagram of a typical slider and head  
5 assembly is shown. The slider 101 is usually made of a  
rigid ceramic material such as alumina-TiC and is attached  
to a flexible metal suspension (not shown). A recording  
head 102 is constructed on the trailing surface 104 of the  
slider 101. The recording head usually comprises a write  
10 element, also known as the write head, and a separate read  
element, also known as the read head. In addition to the  
recording head there are metallic pads 103 used to make  
electrical connections to the recording head. One side 105  
of the slider is designed to be in close proximity to a  
15 disk and has air bearing features.

Fig. 2a shows some of the layers of a conventional  
read element 200 which utilizes the spin-valve (or GMR)  
effect. A layer which comprises an antiferromagnetic (AFM)  
material 201 is placed on a substrate layer 202. The  
20 substrate layer can be an insulating layer or an adhesion  
or seed layer. The AFM material can be chosen from a range  
of materials including but not limited to PtMn, NiMn, IrMn,  
PdMn, and NiO. A pinned layer 203 is then placed on the AFM



layer. A thin nonmagnetic, electrically conductive layer 204, usually copper, is then placed on the pinned layer. A free layer 205 is then placed on the nonmagnetic layer 204. The free layer is usually, but not limited to, a

5 ferromagnetic alloy such as NiFe, CoFe, or CoNiFe. Finally, a pair of stabilization tabs 206 are formed on a surface of the free layer 205. The tabs 206 define the track width and provide longitudinal magnetic stabilization for the free

10 layer. The material in the tabs 206 may be either a hard magnetic material such as an alloy typically comprising cobalt and platinum, or an AFM material such as PtMn which exchange couples with a portion of the free layer. The view of Fig. 2a is that of the sensor as presented to the disk in a disk drive. To achieve a nearly linear response it is

15 desired that the direction of the magnetization 207 in the free layer be substantially parallel to the disk. This is true of all conventional GMR sensors used in magnetic recording. In a GMR sensor it is also desired that the magnetization of the pinned layer be substantially

20 perpendicular to the magnetization of the free layer. Accordingly the magnetization of the pinned layer 208 is shown perpendicular to that of the free layer 207 and also perpendicular to the surface of the disk.

Fig. 2b shows the stack of sensor layers as positioned between the magnetic shields 209. The purpose of the shields is to restrict the spatial sensitivity of the sensor to a very limited area on the disk. The sensor stack  
5 is electrically insulated from the shields by insulating layers 210. In order to extract the electrical signal from the sensor, current 211 is passed through electrical leads 212 through the sensor stack. The direction of the current 211 is parallel to the free layer 205 and is perpendicular  
10 to the track direction.

The sensor 200 shown in Fig. 2a has a pinned layer which is comprised of substantially one magnetic layer. This structure is generally called a simple spin valve or simple GMR structure. One difficulty with the simple GMR  
15 structure is that there is a noticeable demagnetization field from the pinned layer. This can cause problems with linearity and restricts the choices of magnetic biasing. These problems are greatly reduced by using a composite structure for the pinned layer comprised of two  
20 ferromagnetic layers separated by a thin nonmagnetic layer in such a way that the two ferromagnetic layers are antiparallel, AP, coupled. This composite structure is called an AP pinned substructure. The ferromagnetic

material is typically an alloy comprising Ni, Fe, and Co. The thin nonmagnetic layer between the two ferromagnetic layers is usually but not limited to ruthenium. A sensor having an AP pinned substructure is called an AP pinned GMR  
5 sensor, or synthetic AFM GMR sensor.

A view of a typical AP pinned GMR structure is shown in Figure 3. Fig. 3 also illustrates a preferred embodiment wherein the two bias stabilization tabs 308 are constructed of an AFM material exchange coupled with selected portions  
10 of the free layer 307. One AFM layer 301 is used for controlling the direction of the first ferromagnetic layer 303 in the AP pinned substructure 309 and a second AFM layer 308 is used for the longitudinal bias of the free layer 307. The AP pinned substructure 309 serves as the  
15 pinned layer of the sensor.

In Fig. 3, an AFM layer 301 is placed on the substrate 302. A first ferromagnetic layer 303 is placed on the AFM layer 301. Then a thin nonmagnetic layer 304 is deposited on the first ferromagnetic layer 303. A second  
20 ferromagnetic layer 305 is then placed on the thin magnetic layer 304. The composite of layers comprising the first ferromagnetic layer 303, the thin nonmagnetic layer 304 and the second ferromagnetic layer 305 is the AP pinned

substructure. The rest of the sensor including the thin nonmagnetic layer 306, the free layer 307, and the bias stabilization tabs 308 serve the same function as in the simple GMR case. Because of the presence of the AP pinned substructure, the sensor in Fig. 3 is generally referred to as an AP pinned GMR.

The direction of the magnetization 320 in the free layer 307 in Fig. 3 is parallel to the surface of the disk (not shown). It is desirable that the net magnetization of the AP pinned substructure 309 is substantially perpendicular to the magnetization 320 in the free layer 307. It is possible for the net magnetization of the AP pinned substructure 309 to be zero. In that case the magnetization of each of the ferromagnetic layers 303,305 in the pinned layer 309 should be substantially perpendicular to that of the free layer 307. Thus in Fig. 3 the magnetization 310 of the first ferromagnetic layer 303 in the AP pinned layer 309 is shown perpendicular to that of the free layer 307 and as coming out of the field of view. Because the two ferromagnetic layers 303,305 in the AP pinned substructure have magnetization directions 310,311 which are substantially at 180 degrees with respect to each other (in the absence of an external field), the

direction of the magnetization 311 of the second  
ferromagnetic layer 305 in the AP pinned substructure 309  
is also perpendicular to the direction of the magnetization  
320 in the free layer 307 but is approximately 180 degrees  
5 relative to the direction of magnetization 310 of the first  
ferromagnetic layer 303. This magnetization 311 is shown  
going into the field of view in Fig. 3.

During the manufacturing of these structures it is  
desirable to establish the appropriate directions of the  
10 magnetization in the first ferromagnetic layer and the free  
layer. In a conventional sensor two different AFM materials  
are chosen so that the blocking temperatures of the two are  
distinctly different. As an example, if the AFM with the  
highest blocking temperature is adjacent to the free layer,  
15 then the conventional method is to first heat the structure  
above the blocking temperature of both of the AFM  
materials. The sensor is then placed in a magnetic field  
along the direction of the free layer which aligns the  
magnetization of the free layer in the proper direction.  
20 The sensor is then cooled below the blocking temperature of  
this AFM layer but held above the blocking temperature of  
the AFM layer adjacent to the pinned layer. While the  
structure is held at this intermediate temperature the

field is rotated 90° relative to the former direction. The assembly is then cooled to ambient temperature. It is critical that an external magnetic field be imposed on the ferromagnetic material as the AFM material cools from a  
5 temperature higher than the blocking temperature to a lower temperature. That particular layer is said to be "set" or initialized.

Another advantage of using the present invention for a sensor such as shown in Fig. 3 is that during processing  
10 the thickness of the free layer 307 under the exchange tabs 308 is not perfectly uniform. The field strength required for the spin-flop effect is typically in the 1000 to 3000 Oe range. This field strength is higher than customary and is sufficient to overcome demagnetization effects from any  
15 nonuniformities in the free layer.

In a typical AP pinned GMR the material for the AFM material can be chosen from a list of AFM materials which include PtMn, NiMn, PdNn, NiO, IrMn and others. These materials must simultaneously meet the demand for good  
20 magnetic performance in addition to an acceptable blocking temperature. In general, sensors having AFM layers with higher blocking temperatures are more robust to deleterious heating effects. A conventional sensor requires two

different materials with two different blocking  
temperatures because of the need for initialization. This  
need compromises both the thermal reliability of the sensor  
and the magnetic performance because of differences in  
5 exchange energy, etc.

The present invention allows the use of the same AFM  
material to be used for setting both the pinned layer and  
the bias of the free layer. Thus the material may be chosen  
for optimal magnetic performance. The key feature in being  
10 able to use the same AFM material is to be able to  
initialize the layers given the same blocking temperature.  
The initialization process makes use of magnetic behavior  
generally referred to as a spin flop effect.

The spin flop effect is illustrated in Fig. 4a-d. In  
15 Fig. 4a the important magnetic layers in the sensor are  
shown including the first AFM exchange layer 401 adjacent  
to the free layer, the free layer 402, the second  
ferromagnetic layer 403 of the AP pinned substructure 409,  
the first ferromagnetic layer 404 of the AP pinned  
20 substructure 409, and the AFM material 405 adjacent to the  
first ferromagnetic layer 404. The AP pinned substructure  
409 serves as the pinned layer of the sensor. Also, the  
magnetization directions are shown. For clarity, the

additional layers are not shown. Fig. 4a shows the directions of magnetization when the structure has been placed in a high magnetic field. The magnetization 406 of the free layer aligns with the applied external field for most practical values of the applied field. For high values of the applied field the antiparallel coupling in the AP pinned substructure is broken and the magnetization of both the first ferromagnetic layer 408 and the second ferromagnetic layer 407 align with the applied field. This magnitude of field is not useful for initialization. As the applied field is reduced, the direction of the magnetizations 407,408 in the AP pinned substructure 409 will begin to rotate in order to seek the lowest energy. Fig. 4b shows the case where the magnetizations in the AP pinned substructure have begun to rotate as the magnitude of the applied field is reduced. The magnetizations 407,408 rotate away from the direction of the applied field and in opposite directions from each other. This behavior is referred to as the spin-flop effect. Fig. 4c shows that at some optimum value of the applied field the magnetization of the first ferromagnetic layer 408 will be perpendicular to the applied field and perpendicular to the magnetization of the free layer which is still aligned with the applied



field. This is the value of the applied field which is used when cooling both AFM layers 401,405 below the blocking temperature to achieve initialization. At the optimum external field value the direction of the second  
5 ferromagnetic layer 407 need not be opposite from the magnetization of the first ferromagnetic layer 408. However when the external field is removed the magnetization of the second ferromagnetic layer 407 will be substantially opposite from that of the first ferromagnetic layer 408.  
10 Without using the spin-flop effect to induce the appropriate rotation it is not practical to use the optimal choice of the same material for the two AFM layers because of the difficulty with initialization.

An example of the angle of the magnetization in the  
15 first ferromagnetic layer 408 in the AP pinned substructure 409 as a function of field magnitude is shown in Fig. 4d. In this case the angle is measured from the desired direction of the final angle. The targeted angle is  $90^\circ$  with respect to the field direction. Therefore the desired  
20 angle as shown in Fig. 4d is  $0^\circ$ . For this specific case, the coupling strength across the ruthenium layer is 0.5 erg/cm<sup>2</sup>, and the moments/area of the first and second ferromagnetic layers are 0.2 and 0.4 memu/cm<sup>2</sup>, respectively.

In this case, the optimum field strength to achieve the spin-flop effect is approximately 2200 Oe. Other structures with different materials, thicknesses, and moments would have a different optimal external field strength.

5       As a practical matter, better process consistency is achieved by first increasing the applied field to a high value and then reducing the magnitude until the optimum value is applied. However it is also possible to place the sensor directly into a field having the optimum value or to  
10       raise the field from an initial value of zero. The actual value of the applied field chosen as the optimum depends to some extent on the choice of AFM material, the thickness of the layers, the coupling strength of the nonmagnetic layer, any annealing temperature, and the geometry of the sensor.  
15       For these reasons the optimum value is usually determined by first performing a process tolerance study using the specific sensor design.

      An alternate embodiment of this invention is shown in Fig. 5. In this case an AFM layer 502 is placed on the  
20       substrate 501. A simple pinned layer 503 is deposited on the AFM layer 502. A thin nonmagnetic layer 504 (e.g. Cu) is placed between the pinned layer 503 and the free layer 505. The biasing tabs 510 for the free layer comprise a

thin nonmagnetic layer 506 (e.g. Ru) which allows antiparallel coupling of another ferromagnetic layer 507 with a portion of the free layer. This antiparallel coupling provides the bias stabilization for the free  
5 layer. The direction 511 of the magnetization in the free layer 505 is approximately  $180^\circ$  relative to the magnetization 512 in the ferromagnetic layer 507 of the bias tab 510. The ferromagnetic portion 507 of the bias tabs must be pinned and this is provided by an AFM layer  
10 508. The AFM layer 508 can be made of the same material as the AFM layer 502 for the pinned layer and is initialized by the same process step described above.

In the discussion of the spin-flop effect illustrated in Fig. 4a-d, the direction of the applied external field  
15 410 is shown along the direction of the long axis of the free layer. This is also parallel to the surface of the disk. However, for the structure shown in Fig. 5 the direction of the initialization field 509 should be perpendicular to the desired direction of magnetization 511  
20 of the free layer 505. This direction aligns the magnetization 513 in the pinned layer 503 and permits the spin-flop effect to rotate the magnetization 512 of the ferromagnetic layer 507 of the bias tabs  $90^\circ$  relative to

the applied field 509. This must be done at the optimum external field strength.

Another alternate embodiment of this invention is shown in Fig. 6. The substrate 601, AFM layer 602, first  
5 ferromagnetic layer 603, thin nonmagnetic layer 604, second ferromagnetic layer 605, thin nonmagnetic layer 606, and free layer 607 are as previously described for an AP pinned sensor. The biasing tabs for the free layer comprise a thin nonmagnetic layer 608 which allows antiparallel coupling of  
10 another ferromagnetic layer 609. This AP pinned substructure for the bias tabs was previously illustrated in Fig. 5. The structure in Fig. 6 therefore has two groups of layers which are AP pinned: one group 603, 604, and 605 for the pinned layer and another group 607, 608, and 609  
15 for the bias stabilization of the free layer. The ferromagnetic portion 609 of the bias tabs must be pinned and this is provided by an AFM layer 610. The AFM layer 610 can be made of the same material as the AFM layer 602 for the pinned layer and is initialized by the same process  
20 step described above. The sensor is cooled below the blocking temperature in the presence of the optimum field to utilize the spin-flop effect.

For the structure in Fig. 6 it is desirable that the

spin-flop effect be operative on only one set of the AP  
pinned substructures. This can be achieved by such means as  
selecting different thicknesses for the thin nonmagnetic  
layers 604, 608, or different thicknesses for the  
5 ferromagnetic layers 603, 605, 609, or a combination of  
these. Depending on the choice of layer thicknesses it is  
possible to have the direction of the initialization field  
either along the sensor direction 611 (using the spin-flop  
effect on the pinned layer) or perpendicular to the disk  
10 direction 612 (using the spin-flop effect on the bias  
stabilization tabs). It is also possible to use an applied  
field direction which is not at 90° but has a magnitude  
which would result in the appropriate angle (see Fig 4d).  
This magnitude and direction could be chosen to accommodate  
15 both AP pinned substructures in Fig. 6a. The important  
feature is that a simple initialization step is required  
with only one externally applied field and one cooling step  
in the presence of this field.

Another embodiment is shown in Fig. 7. The sensor  
20 shown in Fig. 7 differs from the sensors shown in the prior  
Figures in that the physical width 720 of the layers  
approximately defines the magnetic trackwidth of the  
sensor. A first AFM layer 703 provides exchange coupling

with the first ferromagnetic layer 704 of the AP pinned substructure 707. The nonmagnetic layer 705 and a second ferromagnetic layer 706 complete the AP pinned substructure 707 which serves as the pinned layer of the sensor. A  
5 nonmagnetic layer 708 usually of copper separates the second ferromagnetic layer 706 of the AP pinned substructure 707 from the free layer 709. A third ferromagnetic layer 711 is separated from the free layer 709 by third nonmagnetic layer 710. The third nonmagnetic  
10 layer may be formed from a number of materials such as Ru or Ta. Ru or Ta is preferred over Cu for layer 710 to minimize possible GMR behavior of the free layer 709, nonmagnetic layer 710, ferromagnetic layer 711 combination. A second AFM layer 712 is exchanged coupled with the third  
15 ferromagnetic layer 711. The stack of layers forming the sensor is connected to electrical leads 713 and is insulated with an insulating material 702 from the magnetic shields 701. The direction of the sense current 715 is indicated. Also the direction 730 of the external field  
20 required to take advantage of the spin-flop effect in indicated. One novel feature of the sensor in Fig. 7 is that bias stabilization of the free layer is accomplished by weakly coupling the third ferromagnetic layer 711

through the third nonmagnetic layer 710. Additionally, the width of the third ferromagnetic layer is approximately the width of the free layer. The width 720 of all the layers in Fig. 7 are shown to be equal. In practice some variation of widths will occur because of processing artifacts.

The process of using the spin-flop effect to achieve a simplified initialization process allows sensors having the same material for the AFM layers to be practical. However initialization using the spin-flop effect could also be used on sensors having two different AFM materials. The only requirement is that the blocking temperature of both AFM layers must be initially exceeded and that the final temperature after the cooling step in the presence of the external field be below the blocking temperature of both materials.

For the purposes of this invention it is immaterial whether the magnetization of the free layer (e.g. 309 in Fig. 3) is pointing left or right. It is also immaterial whether the magnetization (310 in Fig. 3) of the first ferromagnetic layer (303 in Fig. 3) is into or out of the field of view. It is also immaterial if during the construction of the sensor, the pinned layer is deposited first and then the free layer is deposited or whether the

order of layers is reversed. However, it is important that the magnetizations of the two ferromagnetic layers (e.g. 310, 311 in Fig. 3) be substantially opposite to each other after the removal of the external field.

5        Figs. 8a and 8b show the present invention as used in a magnetic recording disk drive. The magnetic recording disk 802 is rotated by drive motor 804 with hub 806, which is attached to the drive motor. The disk comprises a substrate, a magnetic layer, an optional overcoat layer  
10    such as carbon, and typically a lubricant layer such as a perfluoropolyether. The substrate is typically either aluminum, glass, or plastic. Some disk drives are designed such that the slider 810 comes to rest on the disk when the disk drive is stopped. In other disk drives, the slider is  
15    lifted off of the disk surface when the disk drive is turned off. The latter is preferable when the surfaces of the slider and the disk are designed to have very low roughness. This is advantageous for designs requiring frequent or continuous contact between the slider and the  
20    disk during normal operation.

A recording head assembly 808 is formed on the trailing surface of a slider 810. The slider has a trailing vertical surface 809. The recording head assembly usually



comprises a separate write element along with the GMR read  
sensor. The slider 810 is connected to the actuator 812 by  
means of a rigid arm 814 and a suspension 816. The  
suspension 816 provides a force which pushes the slider  
5 toward the surface of the recording disk 802.

While the invention has been described above in  
connection with preferred embodiments thereof and as  
illustrated by the drawings, those with skill in the art  
will readily recognize alternative embodiments of the  
10 invention can be easily produced which do not depart from  
the spirit and scope of the invention as defined in the  
following claims.